

The Grothendieck group as a classification tool for algebras

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① Some simple relations between matrices

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- 2 Grothendieck groups and K -theory

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- 4 Classifications of Leavitt path algebras via K -theory

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$A = 2, B = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$. Then $A \sim_E B$ as

$$\begin{aligned}2 &= (1 \ 1) \begin{pmatrix} 1 \\ 1 \end{pmatrix} \\ \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} &= \begin{pmatrix} 1 \\ 1 \end{pmatrix} (1 \ 1)\end{aligned}$$

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The equivalence relation generated by \sim_E is called **strongly shift equivalent**, denoted by \sim_S , i.e., $A \sim_S B$ if

$$A = A_0 \sim_E A_1 \sim_E A_2 \sim_E \cdots \sim_E A_n = B.$$

Example

Let $A = \begin{pmatrix} 1 & 3 \\ 2 & 1 \end{pmatrix}$ and $B = \begin{pmatrix} 1 & 6 \\ 1 & 1 \end{pmatrix}$. Question: $A \sim_S B$?

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$$A_3 = \begin{pmatrix} 1 & 2 & 1 & 1 \\ 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 \\ 2 & 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 2 & 0 & 0 & 1 \\ 1 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 \end{pmatrix}$$

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Example

$$\begin{pmatrix} 1 & 3 \\ 2 & 1 \end{pmatrix} \sim_E A_1 \sim_E A_2 \sim_E A_3 \sim_E A_4$$

$$\begin{pmatrix} 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 2 & 0 & 0 & 1 \\ 0 & 2 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 1 & 1 \\ 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 \\ 2 & 0 & 0 & 1 \end{pmatrix} = A_3$$

$$A_3 = \begin{pmatrix} 1 & 2 & 1 & 1 \\ 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 \\ 2 & 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 2 & 0 & 0 & 1 \\ 1 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 2 & 0 & 0 & 1 \\ 1 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 2 & 0 \\ 1 & 1 & 1 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 2 & 1 & 0 \end{pmatrix} = A_4$$

Example

$$\begin{pmatrix} 1 & 3 \\ 2 & 1 \end{pmatrix} \sim_E A_1 \sim_E A_2 \sim_E A_3 \sim_E A_4 \sim_E A_5$$

$$\begin{pmatrix} 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 2 & 0 & 0 & 1 \\ 0 & 2 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 1 & 1 \\ 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 \\ 2 & 0 & 0 & 1 \end{pmatrix} = A_3$$

$$A_3 = \begin{pmatrix} 1 & 2 & 1 & 1 \\ 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 \\ 2 & 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 2 & 0 & 0 & 1 \\ 1 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 2 & 0 & 0 & 1 \\ 1 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 2 & 0 \\ 1 & 1 & 1 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 2 & 1 & 0 \end{pmatrix} = A_4$$

$$A_4 = \begin{pmatrix} 1 & 2 & 2 & 0 \\ 1 & 1 & 1 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 2 & 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 & 1 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 1 & 0 & 1 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 3 & 0 & 2 & 2 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \end{pmatrix} = A_5$$

Example

$$\begin{pmatrix} 1 & 3 \\ 2 & 1 \end{pmatrix} \sim_E A_1 \sim_E A_2 \sim_E A_3 \sim_E A_4 \sim_E A_5$$

$$\begin{pmatrix} 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 2 & 0 & 0 & 1 \\ 0 & 2 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 1 & 1 \\ 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 \\ 2 & 0 & 0 & 1 \end{pmatrix} = A_3$$

$$A_3 = \begin{pmatrix} 1 & 2 & 1 & 1 \\ 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 \\ 2 & 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 2 & 0 & 0 & 1 \\ 1 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 2 & 0 & 0 & 1 \\ 1 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 2 & 0 \\ 1 & 1 & 1 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 2 & 1 & 0 \end{pmatrix} = A_4$$

$$A_4 = \begin{pmatrix} 1 & 2 & 2 & 0 \\ 1 & 1 & 1 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 2 & 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 & 1 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 1 & 0 & 1 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 3 & 0 & 2 & 2 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \end{pmatrix} = A_5$$

$$A_5 = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 3 & 0 & 2 & 2 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 1 & 1 \\ 3 & 0 & 2 & 2 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

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Example

$$\begin{pmatrix} 1 & 3 \\ 2 & 1 \end{pmatrix} \sim_E A_1 \sim_E A_2 \sim_E A_3 \sim_E A_4 \sim_E A_5 \sim_E A_6$$

$$\begin{pmatrix} 0 & 1 & 1 & 1 \\ 3 & 0 & 2 & 2 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 \\ 5 & 0 & 5 \\ 1 & 0 & 1 \end{pmatrix} = A_6$$

$$A_6 = \begin{pmatrix} 1 & 1 & 1 \\ 5 & 0 & 5 \\ 1 & 0 & 1 \end{pmatrix}$$

Example

$$\begin{pmatrix} 1 & 3 \\ 2 & 1 \end{pmatrix} \sim_E A_1 \sim_E A_2 \sim_E A_3 \sim_E A_4 \sim_E A_5 \sim_E A_6$$

$$\begin{pmatrix} 0 & 1 & 1 & 1 \\ 3 & 0 & 2 & 2 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 \\ 5 & 0 & 5 \\ 1 & 0 & 1 \end{pmatrix} = A_6$$

$$A_6 = \begin{pmatrix} 1 & 1 & 1 \\ 5 & 0 & 5 \\ 1 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 5 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 & 1 \\ 1 & 0 & 1 \end{pmatrix}$$

Example

$$\begin{pmatrix} 1 & 3 \\ 2 & 1 \end{pmatrix} \sim_E A_1 \sim_E A_2 \sim_E A_3 \sim_E A_4 \sim_E A_5 \sim_E A_6$$

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Some relations among matrices

Question

$$\text{Let } A_k = \begin{pmatrix} 1 & k \\ k-1 & 1 \end{pmatrix} \text{ and } B_k = \begin{pmatrix} 1 & k(k-1) \\ 1 & 1 \end{pmatrix}.$$

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Let $A_k = \begin{pmatrix} 1 & k \\ k-1 & 1 \end{pmatrix}$ and $B_k = \begin{pmatrix} 1 & k(k-1) \\ 1 & 1 \end{pmatrix}$. We showed that

$$A_3 \sim_S B_3.$$

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Is

$$A_k \sim_S B_k,$$

for $k \geq 4$?

Some relations among matrices

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A, B : two square non-negative integer matrices.

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Definition

$A \sim B$, *shift equivalent* if $\exists R, S$: non-negative integer matrices such that for $i > 0$,

$$A^i = RS$$

$$B^i = SR$$

$$AR = RB, \quad SA = BS.$$

Some relations among matrices

Some relations among matrices

R. Williams, **Classification of shift of finite type**, Ann. of Math.
1973.

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Theorem (R. Williams)

- 1 $A \sim_E B$ implies $A \sim B$.
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Counterexample (Kim, Rousch, William's conjecture is false, Ann. of Math. 1992)

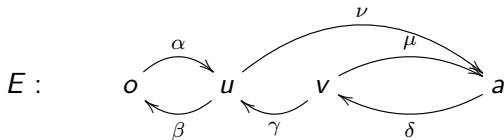
$A \sim B$ does not imply $A \sim_S B$.

Pictorial approach

Graphs

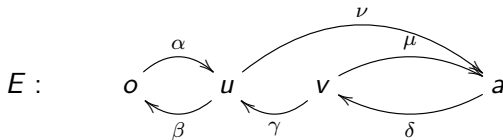
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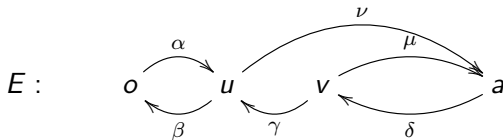
Graphs



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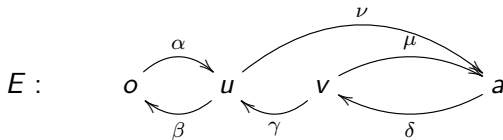
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Pictorial approach

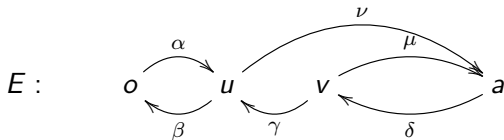
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A non-negative square matrix \iff finite directed graph

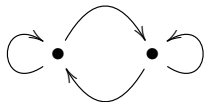
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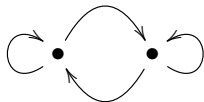
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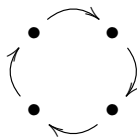
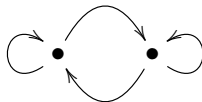
$$\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$
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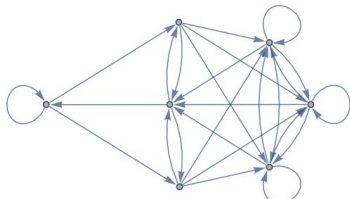
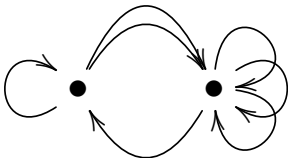
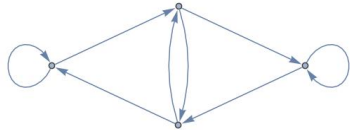
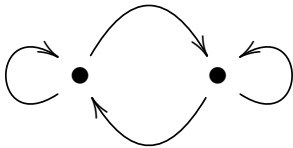
Change of graph

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Matrices \iff Graphics

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$A \sim_S B$ if and only if there is a sequence of insplit and outsplit from A to B .

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Invariants: Let A be a $n \times n$ non-negative square matrix.

$$\begin{array}{ccccccc}
 \mathbb{Z}^n & \xrightarrow{A} & \mathbb{Z}^n & \xrightarrow{A} & \mathbb{Z}^n & \xrightarrow{A} & \dots \\
 \downarrow A & & \downarrow A & & \downarrow A & & \\
 \mathbb{Z}^n & \xrightarrow{A} & \mathbb{Z}^A & \xrightarrow{A} & \mathbb{Z}^n & \xrightarrow{A} & \dots
 \end{array}
 \qquad
 \begin{array}{c}
 \vdots \\
 \delta_A \\
 \downarrow
 \end{array}$$

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$$\begin{array}{c}
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Theorem (W. Krieger, Dimension function and topological Markov chains, Invent. Math, 1980)

$A \sim B$ if and only if $(\Delta_A, \Delta_A^+, \delta_A) \cong (\Delta_B, \Delta_B^+, \delta_B)$.

Summary

Strongly shift equivalent \sim_S :

- Graph characterisation \checkmark
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Grothendieck group K_0

Let A be a ring with identity.

$$\mathcal{V}(A) = \{ [P] \mid P \text{ is f.g projective } A\text{-module} \}$$

This is a monoid with direct sum as addition.

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$$K_0(A) = \mathcal{V}(A)^+.$$

$K_0(A)$ is a pre-ordered abelian group with an order unit $[A]$.

Ultramatricial algebras

Ulramatrical algebras

Definition (Matricial/Ulramatrical algebras)

Let K be a field. Then $\mathbb{M}_{n_1}(K) \times \cdots \times \mathbb{M}_{n_l}(K)$ is called a **matricial algebra**.

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Example

$$K \longrightarrow \mathbb{M}_2(K) \longrightarrow \mathbb{M}_4(K) \longrightarrow \cdots$$

$$a \longmapsto \begin{pmatrix} a & 0 \\ 0 & a \end{pmatrix}$$

$$K \oplus K \longrightarrow \mathbb{M}_2(K) \oplus K \longrightarrow \mathbb{M}_3(K) \oplus \mathbb{M}_2(K) \longrightarrow \cdots$$

$$(a, b) \longmapsto \left(\begin{pmatrix} a & 0 \\ 0 & b \end{pmatrix}, a \right)$$

Classification of Ultramatricial algebras

Theorem (Bratteli, Elliott, Goodearl)

Let R and S be ultramatricial K -algebra. Then $R \cong S$ as K -algebra if and only if

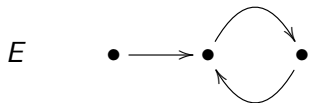
$$(K_0(R), K_0(R)_+, [R]) \cong (K_0(S), K_0(S)_+, [S]).$$

Classification of LPAs via K -groups

Classification of LPAs via K-groups



$$\mathcal{L}(F) \cong \mathbb{M}_3(K)$$



$$\mathcal{L}(E) \cong \mathbb{M}_3(K[x, x^{-1}])$$

Classification of LPAs via K-groups

$$F \quad \bullet \longrightarrow \bullet \longrightarrow \bullet \quad \mathcal{L}(F) \cong \mathbb{M}_3(K)$$

$$E \quad \bullet \longrightarrow \bullet \begin{array}{c} \curvearrowright \\ \curvearrowleft \end{array} \bullet \quad \mathcal{L}(E) \cong \mathbb{M}_3(K[x, x^{-1}])$$

$$\left(K_0(\mathcal{L}(F)), K_0(\mathcal{L}(F))_+, [\mathcal{L}(F)] \right) \cong (\mathbb{Z}, \mathbb{N}, 3)$$

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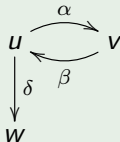
But

$$\mathbb{M}_3(K) \not\cong \mathbb{M}_3(K[x, x^{-1}]).$$

So K_0 doesn't seem to classify **all types** of LPAs.

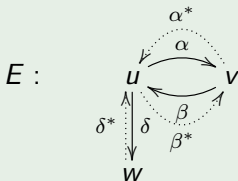
G. Abrams, G. Aranda Pino, **The Leavitt path algebra of a graph**,
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Example (Double of a graph)

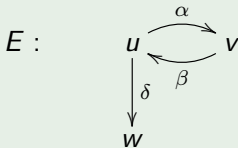


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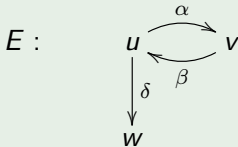
Example (Double of a graph)



Example (Relations in Leavitt path algebra)

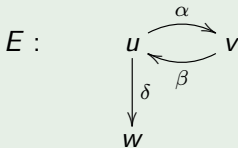


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$$\alpha\beta\alpha \in \mathcal{L}(E),$$

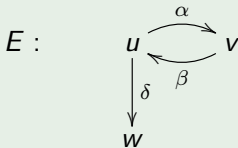
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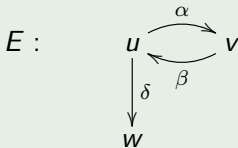
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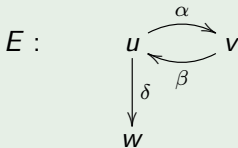


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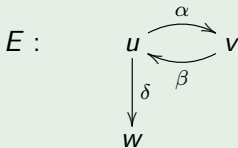


$$\alpha\beta\alpha \in \mathcal{L}(E),$$

$$\alpha^*\alpha = v,$$

$$\alpha\alpha^* + \delta\delta^*$$

Example (Relations in Leavitt path algebra)



$$\alpha\beta\alpha \in \mathcal{L}(E),$$

$$\alpha^*\alpha = v,$$

$$\alpha\alpha^* + \delta\delta^* = u.$$

Definition

For a graph E , let $\mathcal{L}(E)$ be the algebra generated by the sets $\{v \mid v \in E^0\}$, $\{\alpha \mid \alpha \in E^1\}$ and $\{\alpha^* \mid \alpha \in E^1\}$ subject to the relations

- 1 $uv = \delta_{u,v}u$ for every $u, v \in E^0$.
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- 3 $\alpha^*\alpha' = \delta_{\alpha\alpha'}r(\alpha)$, for all $\alpha, \alpha' \in E^1$.
- 4 $\sum_{\{\alpha \in E^1, s(\alpha)=v\}} \alpha\alpha^* = v$ for every $v \in E^0$ for which $s^{-1}(v)$ is non-empty.

Leavitt path algebras: Algebras we can see

Theorem (Abrams, Aranda Pino, 2005)

$\mathcal{L}_K(E)$ is *simple* if and only if

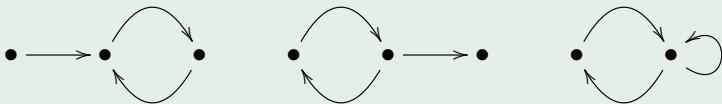
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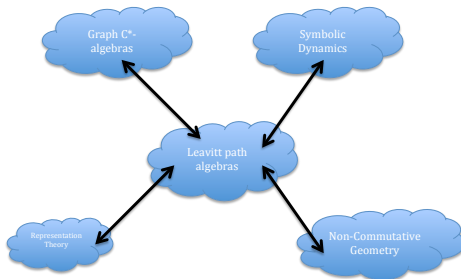
- 1 Every vertex connects to every cycle and to every sink in E , and
- 2 Every cycle in E has an exit.

Example

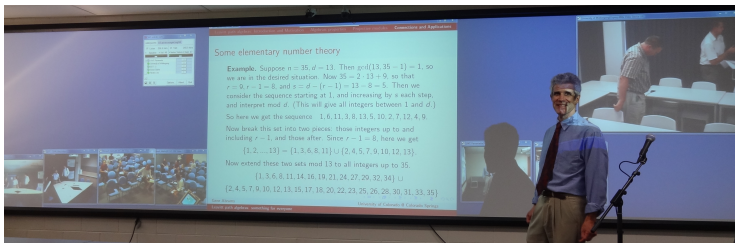
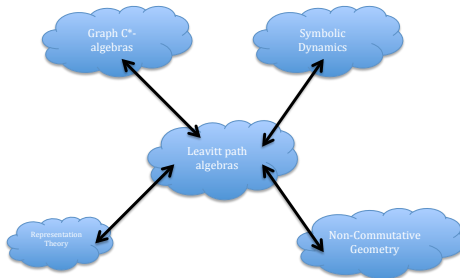


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Gene Abrams at UWS, Feb 2013.

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Towards grading of LPAs

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Example (Acyclic graphs)

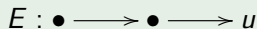
$$F : \bullet \longrightarrow \begin{array}{c} \bullet \\ \downarrow \\ u \end{array}$$

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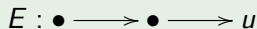
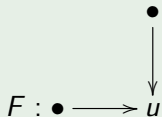
$$\mathcal{L}(F) \cong \mathcal{L}(E) \cong \mathbb{M}_3(K).$$

Towards grading of LPAs

- Taking grading into account...

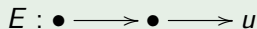
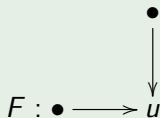
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Example (Acyclic graphs with the **grading**)



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Example (Acyclic graphs with the **grading**)



Then

$$\mathcal{L}(F) \cong_{\text{gr}} \mathbb{M}_3(K)(0, 1, 1)$$

$$\mathcal{L}(E) \cong_{\text{gr}} \mathbb{M}_3(K)(0, 1, 2).$$

Graded Grothendieck group K_0^{gr}

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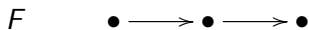
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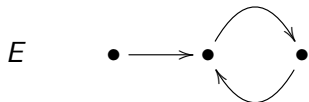
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The group $\mathcal{V}^{\text{gr}}(A)^+$ is called the **graded Grothendieck group** and is denoted by $K_0^{\text{gr}}(A)$, which is a $\mathbb{Z}[\Gamma]$ -module.

Graded versus non-graded K -theory



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$$\mathcal{L}(E) \cong M_3(K[x, x^{-1}])$$

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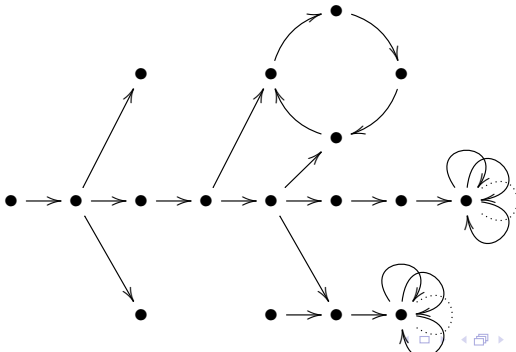
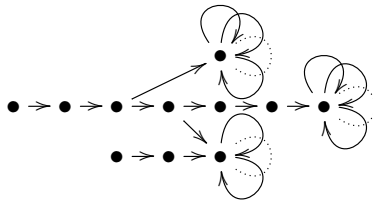
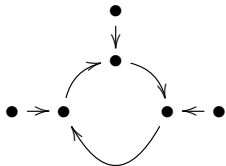
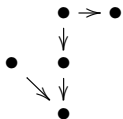
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$$K_0^{\text{gr}}(\mathcal{L}(F)) \cong \bigoplus_{\mathbb{Z}} \mathbb{Z},$$

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Polycephaly graphs



Conj: Graded K-theory classifies all LPAs

Theorem

Let E and F be polycephaly graphs. Then $\mathcal{L}(E) \cong_{\text{gr}} \mathcal{L}(F)$ if and only if there is a $\mathbb{Z}[x, x^{-1}]$ -module isomorphism

$$(K_0^{\text{gr}}(\mathcal{L}(E)), [\mathcal{L}(E)]) \cong (K_0^{\text{gr}}(\mathcal{L}(F)), [\mathcal{L}(F)]).$$

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Theorem (Ara, Pardo, 2014, *J. K-theory*)

A weak version of the conjecture is valid for finite graphs with no sinks and sources.

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